ProbGraph: High-Performance and High-Accuracy Graph Mining with Probabilistic Set Representations

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Motivation

- Graph mining is slow
 - Hard to parallelize since there exists little locality and irregularities in some graphs
- Useful to many problems in modern graphs
 - Examples: Triangle Counting, Clique Counting, Vertex Similarity, Graph Clustering

Contributions

- Provides an approximate algorithm trading accuracy for speed
- Helps general class of graph problems requiring set intersections in their routines.
- Approximation is tunable, and claims up to 50x speedups with up to 90% accuracy

Data Review

 Claims appear to lack support in their data, there is high variance, and not a clear link on how they get 98% or 90% accuracy claims.

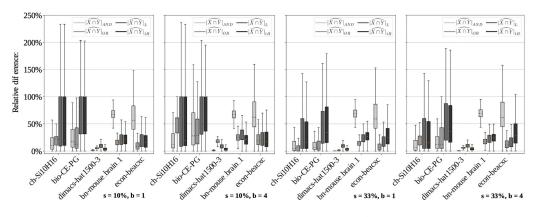
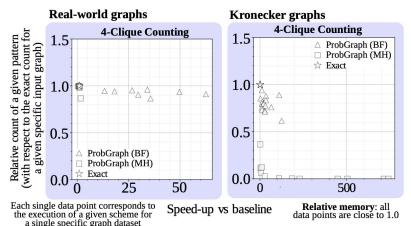
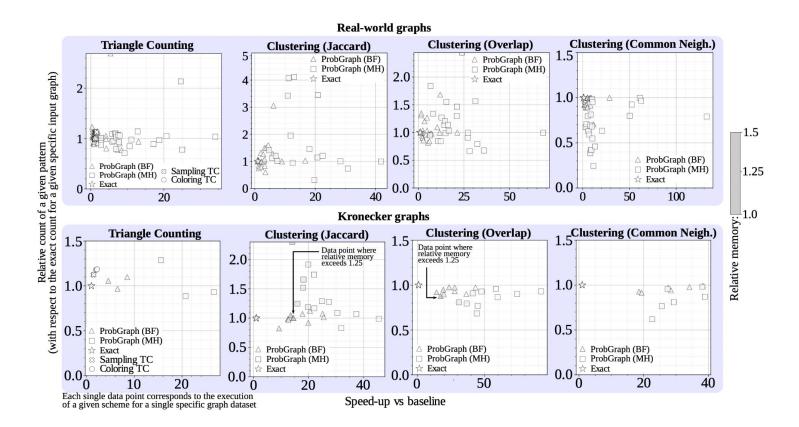


Fig. 3: Analysis of the accuracy of PG estimators of $|X \cap Y|$.



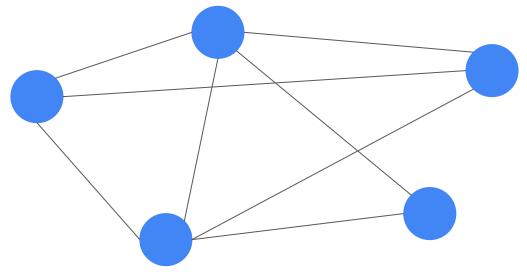
Additional Data Review



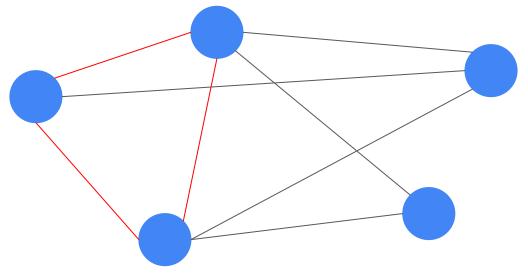
Overview

- Provide background on triangle counting to use as a motivating example
- Recognize a common subroutine in computation is set intersections
- Delve into Bloom Filters and MinHash approximation algorithms
- Show approximation algorithm given in ProbGraph

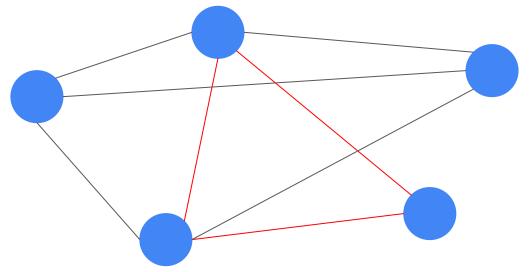
- Find all unique triples such that each pair of vertices shares and edge.
- Used to analyze real world graphs: cluster coefficient, spam filtering, find structure
- There is an n³ algorithm: enumerate all triples and check



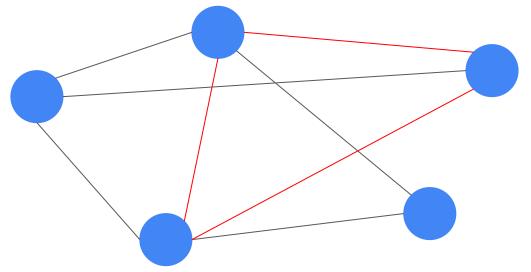
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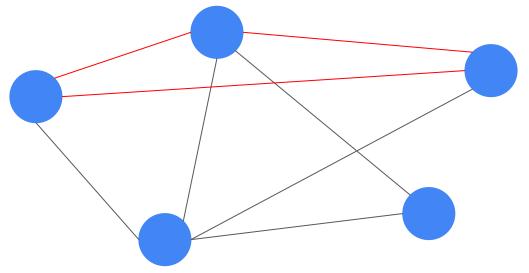
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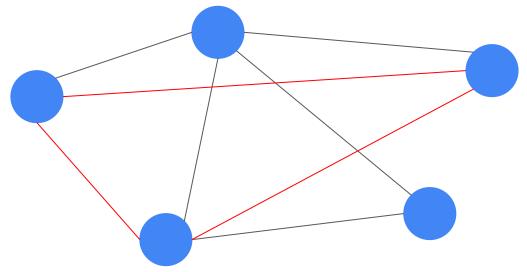
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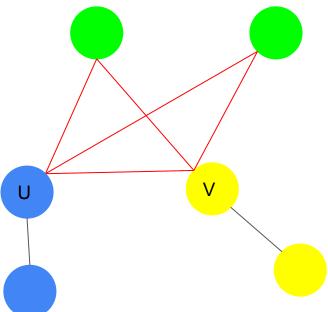


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Triangle Counting Faster Approach

- Let U, V be neighboring vertices and N_x be the neighbors of x
- Then N_U ∩ N_V / {U, V} are triangles



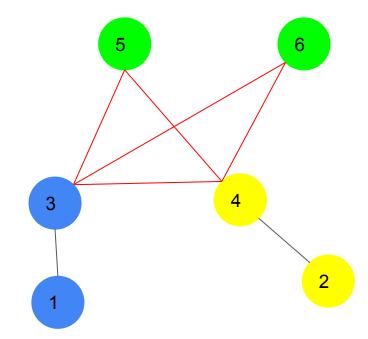
Triangle Counting Algorithm

```
// Derive a vertex order R s.t if R(v) < R(u) then d_v \le d_u for v \in V do: N_v^+ = \{u \in N_v \mid R(v) < R(u)\}

tc = 0

for v \in V do:
	for u \in N_v^+ do: tc += |N_v^+ \cap N_v^+|
```

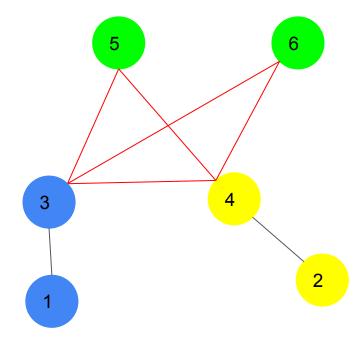
- Let d be max degree and n be number of nodes
- Initial loop takes O(nd)
- Main loop takes O(nd²)



Triangle Counting Parallel Algorithm

```
// Derive a vertex order R s.t if R(v) < R(u) then d_v \le d_u for v \in V [in par] do: N_v^+ = \{u \in N_v \mid R(v) < R(u)\}

tc = 0
for v \in V [in par] do:
for u \in N_v^+ [in par] do: tc += |N_v^+ \cap N_v^+|
```



Other examples

- Clique Counting
- Vertex Similarity
- Graph Clustering

Listing 2: Reformulated 4-Clique Counting.

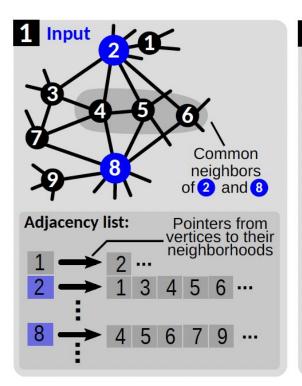
Listing 2: Reformulated 4-Clique Counting.

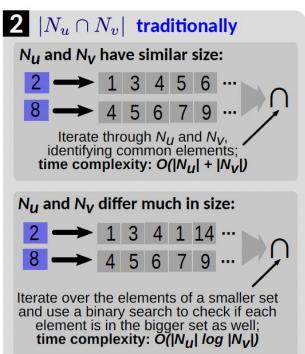
```
1 /* Input: A graph G=(V,E). Output: Clustering C\subseteq E 2 * of a given prediction scheme. */ 3 //Use a similarity S_C(v,u)= |N_v\cap N_u| (see Listing 3). 4 for e=(v,u)\in E [in par] do: //\tau is a user-defined threshold 5 if |N_v\cap N_u|>\tau: C U= \{e\} 6 //Other clustering schemes use other similarity measures.
```

Listing 4: Jarvis-Patrick clustering.

Bottleneck

• $|X \cap Y|$ is slow





How to make $|X \cap Y|$ faster?

- Trading some accuracy for speed
- Use of Bloom Filters and MinHash sets to approximate these intersections

Bloom Filter

- Want space efficient/fast answering to membership queries
- False positives
- Bloom filter has L element bit vector
 - Set of hashes, {h_i}, computes an integer in [1, L]
- Add Element
 - Compute each hash, set corresponding bit to 1
- Retrieve Element
 - Compute each hash, if all 1, return True

2 hashes, $L \in [1, 3]$

Insert a -> {1, 1} BF = 100 Insert b -> {3} BF = 101

Now c -> {1, 3} would be "contained" although not inserted

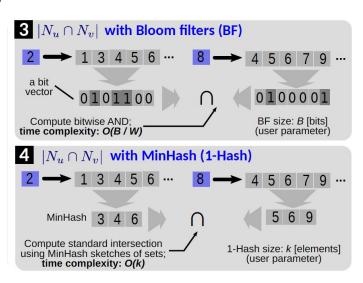
MinHash

- Take k hashes, h₁, h₂,.... h_k
- Compute hash for each element
- Keep values that produce the smallest per hash values
- Variant (1-Hash): keep k smallest hash values using 1 hash function

```
\{\min \{h_1\}, \min \{h_2\}, ..., \min \{h_k\}\}\ or \{\min \{h\}, \min \{h\} / \min \{h\}, ...\}
```

Approximating Intersections

- Two Options:
 - Take bitwise and of Bloom Filter and compute popcount
 - Find intersection of smaller MinHash sets



Size of bloom filter (B), cache word size (W), size of MinHash set (k)

ProbGraph Implementation

- Set a storage limit as a percentage of the graph size
- Now Bloom Filter and MinHash representations exist for the neighborsets of every node with parameters chosen not to exceed this size limit.
- Choose what approximate algorithm you would like to use.
- Very fast to compute as both approximations are much smaller than original neighbor sets.
- Additionally BF is easily vectorized.

```
1 //Input: Graph G, two vertices u and v 2 //Create a standard CSR graph with G as the input graph 3 CSRGraph g = CSRGraph(G); 4 //Create a ProbGraph representation of G based on Bloom filters 5 ProbGraph pg = ProbGraph(g, BF, 0.25); //Use the 25% storage budget 6 7 //Derive the exact intersection cardinality |N_u \cap N_v| 8 int interEX = pg.int_card(g.N(u), g.N(v)); 9 //Derive the estimator |N_u \cap N_v|_{AND} 10 int interBF = pg.int_BF_AND(pg.N(u), pg.N(v)); 11 2 //Compute the exact Jaccard coefficient between u and v 13 double jacEX = interEX / (g.N(u).size() + g.N(v).size() - interEX) 4 //Compute the approximate Jaccard coefficient based on BF 15 double jacBF = interBF / (g.N(v).size() + g.N(v).size() - interPG)
```

Listing 5: Obtaining exact and approximate Jaccard (see Listing 3)

Questions ?