# **Engineering a Cache-Oblivious Sorting Algorithm (Brodal et al.)**

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## **Motivation**

- Sorting is a fundamental problem.
- Cache obliviousness provides guarantees regardless of cache spec.
	- No need to fine tuning.
	- No need for parameter dependence.

# **Set up**

- Working in the RAM model, assuming input sizes that fit in RAM.
- Target runtime (in cache misses):  $O(N/B \log(M)$  (N))
	- M is size of cache
	- $\circ$  B is size of the cache line
	- N is size of input
- Need the (weaker) tall cache assumption:  $M > B^{(1+c)}$ , c  $> 0$  (Brodal et al)
	- Pays additional cost factor of 1/c
	- $\circ$  Standard tall cache assumption: M  $>$  B<sup> $\wedge$ </sup>2

# **Algorithm**

#### **Main algorithm:**

- 1. **Split** N into N^(1/d) segments of size N^(1-1/d) each
- 2. **Sort** each segment **recursively** (use standard sort for base case)
- 3. Apply a **(N^(1/d))-merger** on the sorted segments.

#### **K-merger algorithm:**

- 1. **Construct** a k-merger tree (16-merger tree shown in figure)
	- a. With carefully constructed **buffer sizes**
- 2. Apply the *fill* procedure enough times to sort
	- a. **Each invocation sorts k^d** elements.

#### **Buffer sizes of a k-merger:**

- 1. Buffer size **at the middle (depth d/2)** of the tree are: a\*d^(3/2)
- 2. Recurse on top and bottom trees.
	- a. 'Van Emde Boas'-style recursion

**Procedure**  $FILL(v)$ while  $v$ 's output buffer is not full **if** left input buffer empty FILL(left child of  $v$ ) if right input buffer empty FILL(right child of  $v$ ) perform one merge step



# **Analysis:**

High level idea:

- Sorting is constrained within one subset of the buffers at a time due to the Van Emde Boas-style recursion of setting buffer sizes.
- See board for intuition

# **Implementation and Experiments**

- Machines used for evaluation:
	- Pentium 4, Pentium III, MIPS 10000, AMD Athlon, Itanium 2
- Merger implementation
	- Recursive vs iterative
- Memory navigation:
	- Pointer based, index arithmetic
- Memory layout:
	- BFS, DFS, Van Emde Boas.
	- Lay out nodes and buffers separately, vs together
- Memory allocation:
	- Custom allocator, standard allocator (only used with pointer-based navigation)
- **● Results of 28 experiments: best choice of parameters:**
	- **○ (1) recursive invocation, (2) pointer-based navigation, (3) vEB layout**
	- **○ (4) nodes and buffers laid out separately, and (5) allocation by the standard allocator.**

### **More parameters!**

- **●** Varying degree of the merger: z = {2..9}
	- **○ Best choice: 4 or 5**
- Merger construction caching
	- Gave speedup of 3-5%
- Buffer size scaling parameter *a*, and *d*.
	- Best choice for *a* = 16, and *d* = 2
- Base-case sorting algorithm
	- Use std::sort

### **Comparisons and baselines**

- Compared against cache aware sorting algorithms as well as quicksort.
- See paper for charts!
- Main takeaway: performance depends on the architecture and the input size
	- In some cases the overhead of funnelsort is not worth the gain
	- For architectures with fast CPUs (where cache misses are costlier in comparison) and large input sizes, Funnelsort wins!

# **Discussion question**

• Can we have an even simpler algorithm?