

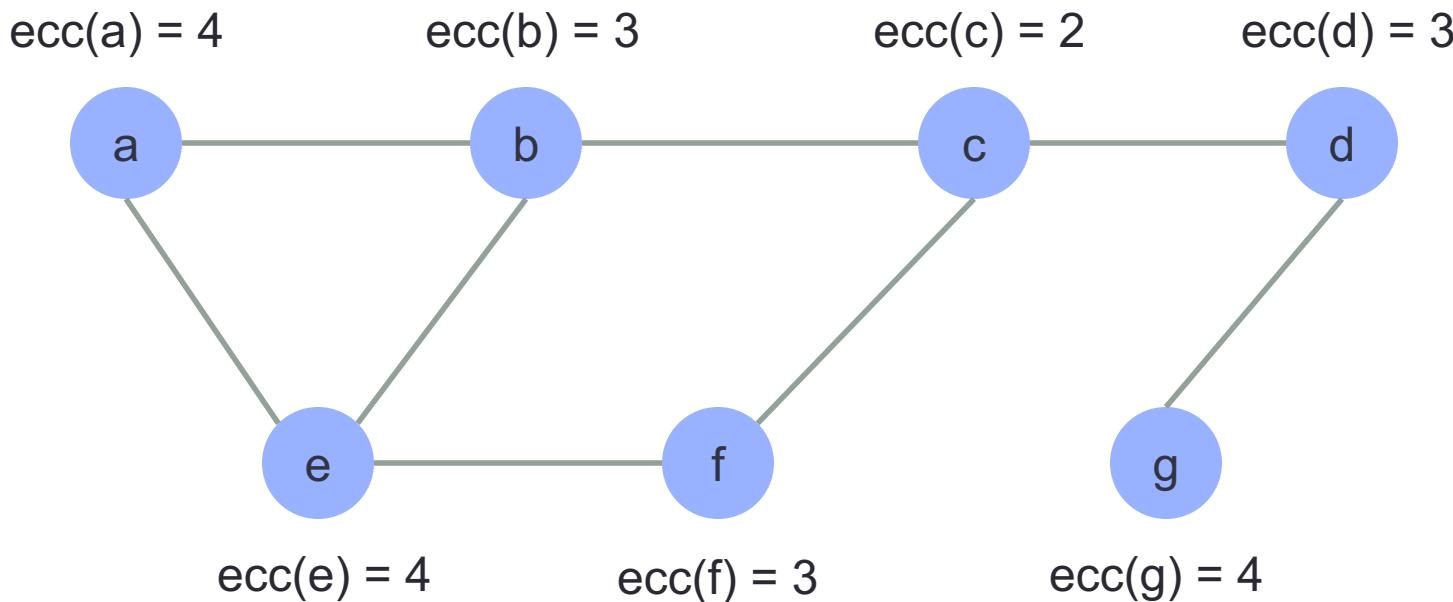
# An Evaluation of Parallel Eccentricity Estimation Algorithms on Undirected Real-World Graphs

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Julian Shun

# Graph Eccentricities

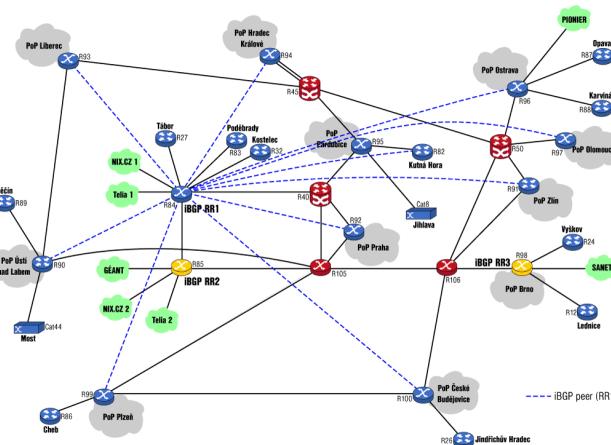
- The **eccentricity** of a vertex  $v$  is the distance to furthest reachable vertex from  $v$



- The **diameter** of a graph is the maximum eccentricity value
- Extends to directed and/or weighted graphs

# Applications

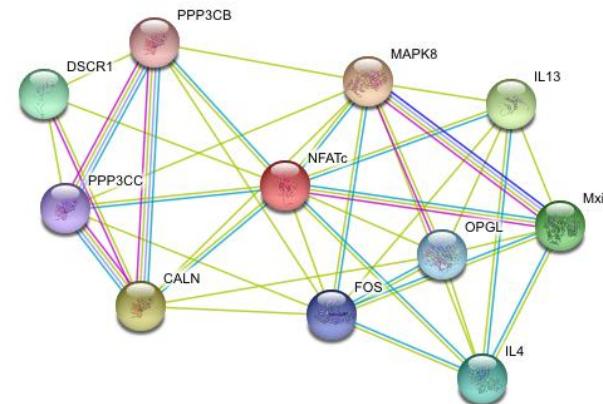
# Routing networks



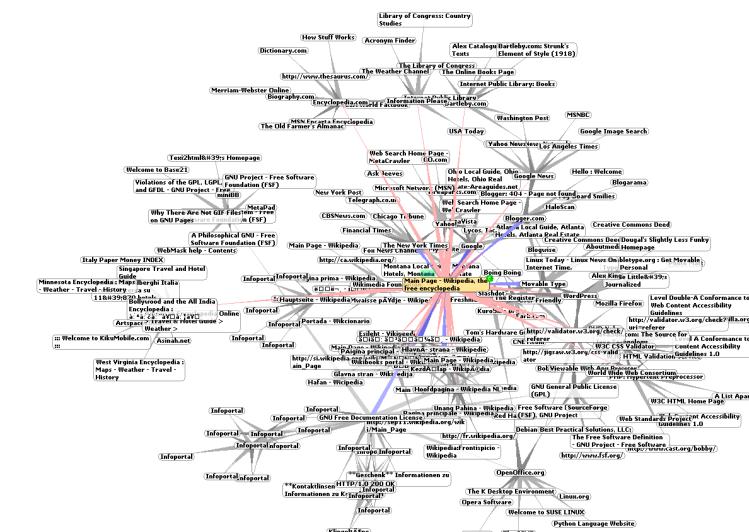
# Social networks



## Protein networks



## Web graphs

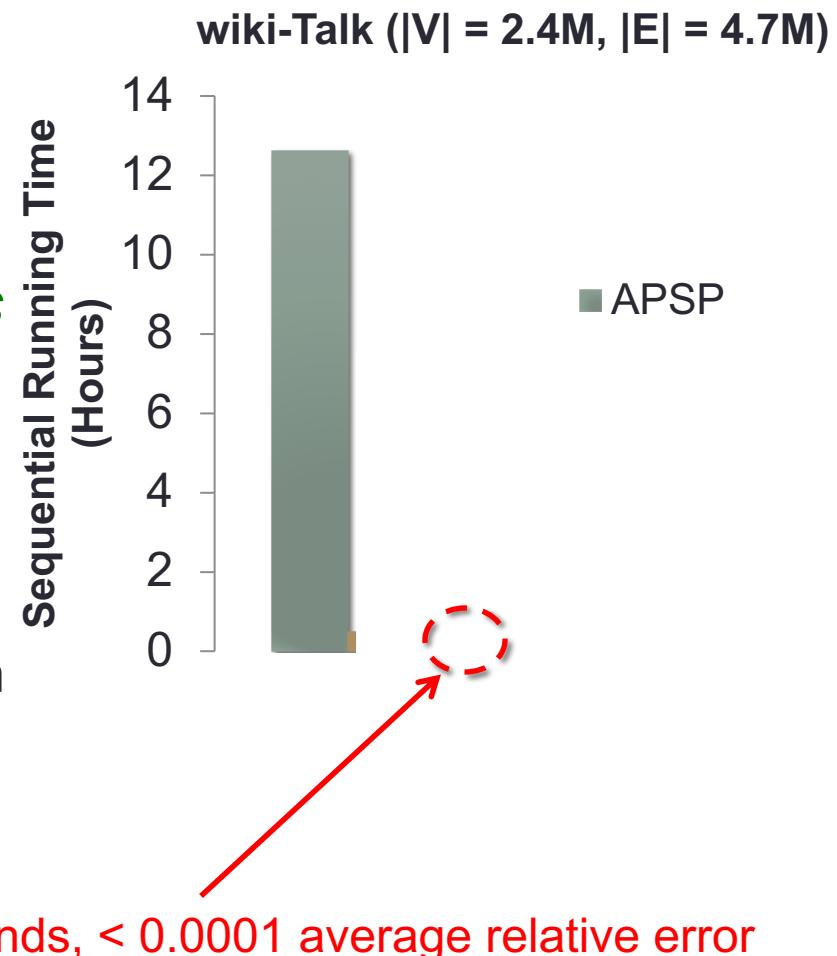


- *Core-periphery structure*

# How to compute eccentricities?

- All pairs shortest paths (APSP)
  - At least quadratic work
  - Would take over 2670 years for Yahoo! Web graph (1.4B vertices, 6.4B edges)
- Takes and Kosters [*Algorithms 2013*] algorithm
  - Quadratic work in the worst case
- Approximation algorithms
  - Orders of magnitude faster
  - Can process Yahoo! Web graph in minutes
- Parallelism

Experiments done on one thread of a 40-core (2.4 GHz) Intel Nehalem machine with 256 GB memory



# This work

- First comprehensive comparison of **parallel** implementations of eccentricity algorithms on **large** (undirected/unweighted) real-world graphs

| Algorithm  | Guarantee   | Complexity                            |
|--|-------------|---------------------------------------|
| APSP   | Exact       | $O( E   V )$                          |
| Takes-Kosters [Algorithms 2013]                        | Exact       | $O( E   V )$                          |
| Single BFS   | 2-approx    | $O( E )$                              |
| Chechik et al. [SODA 2014]                             | 1.66-approx | $O( E  ( V  \log  V )^{1/2})$         |
| Roditty-Vassilevska Williams [STOC 2013]               | 1.5-approx  | $O( E  ( V  \log  V )^{1/2})$         |
| ANF/HADI [Palmer et al. KDD '02, Kang et al. TKDD '10] |             | $O(k  E  D)$                          |
| HyperANF [Boldi et al. WWW 2011]                       |             | $O(k (\log \log  V /\log  V )  E  D)$ |
| k-BFS [this work]                                      |             | $O(k  E  \min(1, D/\log  V ))$        |

$|V|$  = # vertices

$|E|$  = # edges

$k$  = # probabilistic counters/BFS's

$D$  = diameter

- Simple shared-memory implementations in the Ligra graph processing framework [Shun and Blelloch PPoPP 2013]
- k-BFS as a parallel primitive for fast, scalable, and accurate eccentricity estimation

# Simple 2-approximation

- **Step 1:** Perform breadth-first search (BFS) from arbitrary vertex  $v$  to compute eccentricity
- **Step 2:** Assign all vertices  $\text{ecc}(v)$
- **Guarantee:**  $\text{ecc}(w)/2 \leq \hat{\text{ecc}}(w) \leq 2 \text{ecc}(w)$  for all  $w$
- BFS complexity is  $O(|E|)$  and easily parallelizable with parallel time proportional to diameter

This algorithm is fast but its estimates are useless!

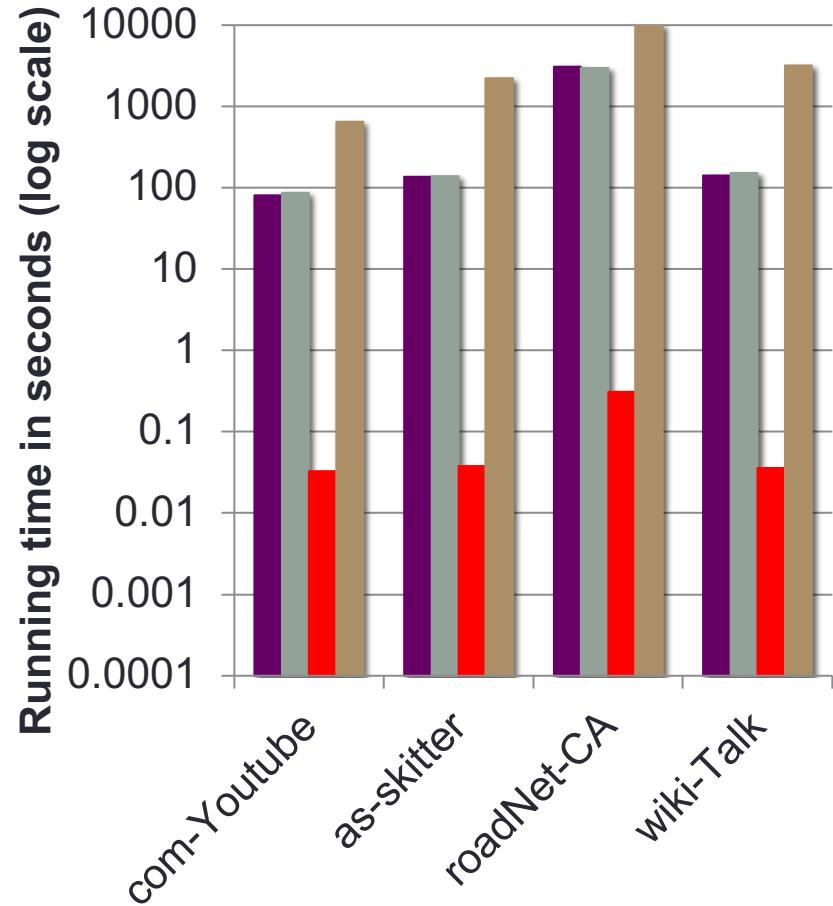
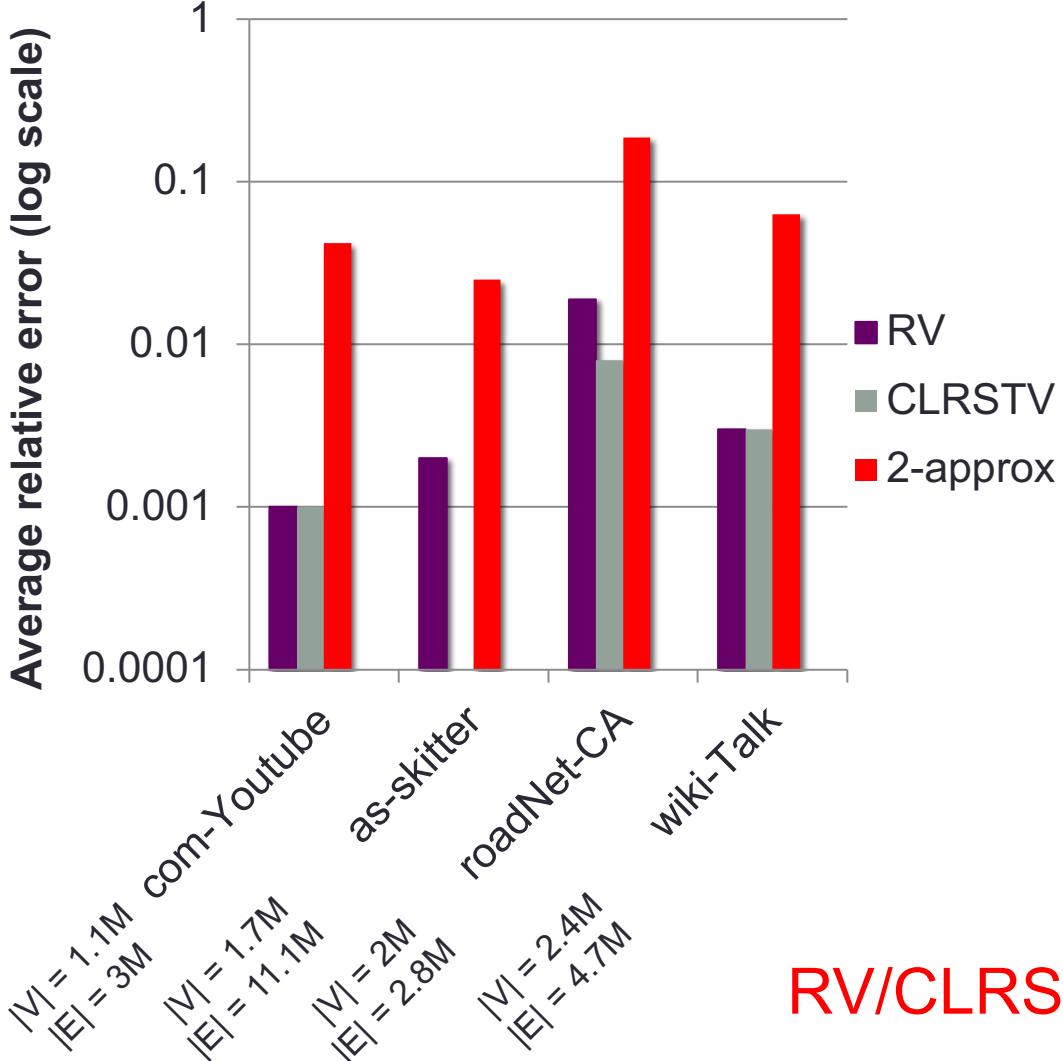
# Stronger provable approx algorithms

- RV: [Roditty-Vassilevska Williams STOC 2013]
  - $(2/3) \text{ecc}(v) \leq \hat{\text{ecc}}(v) \leq (3/2) \text{ecc}(v)$
  - Complexity:  $O(|E| (|V| \log |V|)^{1/2})$
- CLRSTV: [Chechik, Larkin, Roditty, Schoenebeck, Tarjan, and Vassilevska Williams SODA 2014]
  - $(3/5) \text{ecc}(v) \leq \hat{\text{ecc}}(v) \leq \text{ecc}(v)$
  - Complexity:  $O(|E| (|V| \log |V|)^{1/2})$
- We provide the first empirical evaluation of these algorithms
  - Shared-memory parallel implementations in Ligra

# How do they perform in practice?

- Average relative error =  $\frac{1}{|V|} \sum_{v \in V} \left| \frac{\hat{ecc}(v) - ecc(v)}{ecc(v)} \right|$

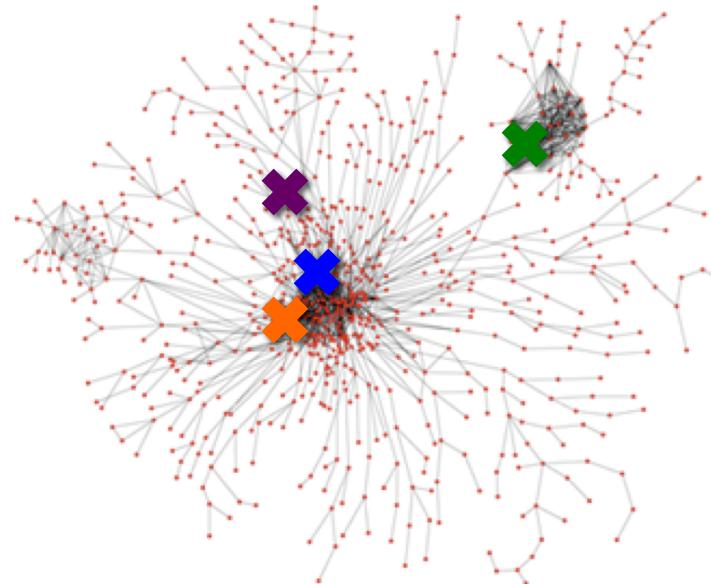
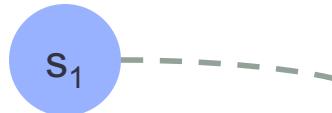
Experiments done on a 40-core Intel Nehalem machine with 256 GB memory



RV/CLRSTV accurate but not scalable

# Multiple BFS's

- Run multiple BFS's from vertices and eccentricity



Source: C.A. Hidalgo, B. Klinger, A.-L. Barabási, R. Hausmann. *Science 317* (2007)

$$\text{ecc}(v) = \max(d(v, s_1), d(v, s_2), d(v, s_3), d(v, s_4)) \quad \text{for all } v$$

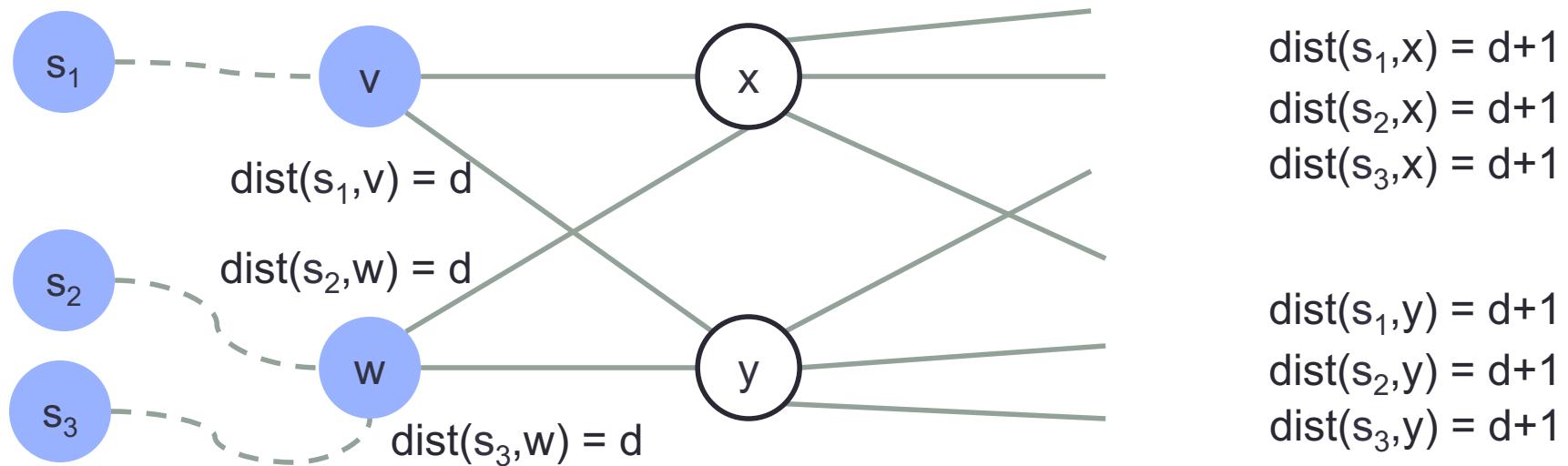
- Does not work that well in practice
- Double-sweep: find furthest vertices from sample of random vertices, then run BFS's from the set of furthest vertices (used before for diameter estimation [Corneil et al. 2001, Magnien et al. 2009])

# k-BFS Implementation (second sweep)

- k BFS sources
- Each vertex  $v$  stores estimate  $\hat{ecc}(v) = 0$
- Run parallel BFS from each source, updating each encountered vertex  $v$  at distance  $d$  to  $\max(\hat{ecc}(v), d)$
- **Observation:** There is shared work among the different BFS's
  - Vertices updated multiple times
  - Vertices placed on frontiers multiple times → edges traversed multiple times

# k-BFS Implementation

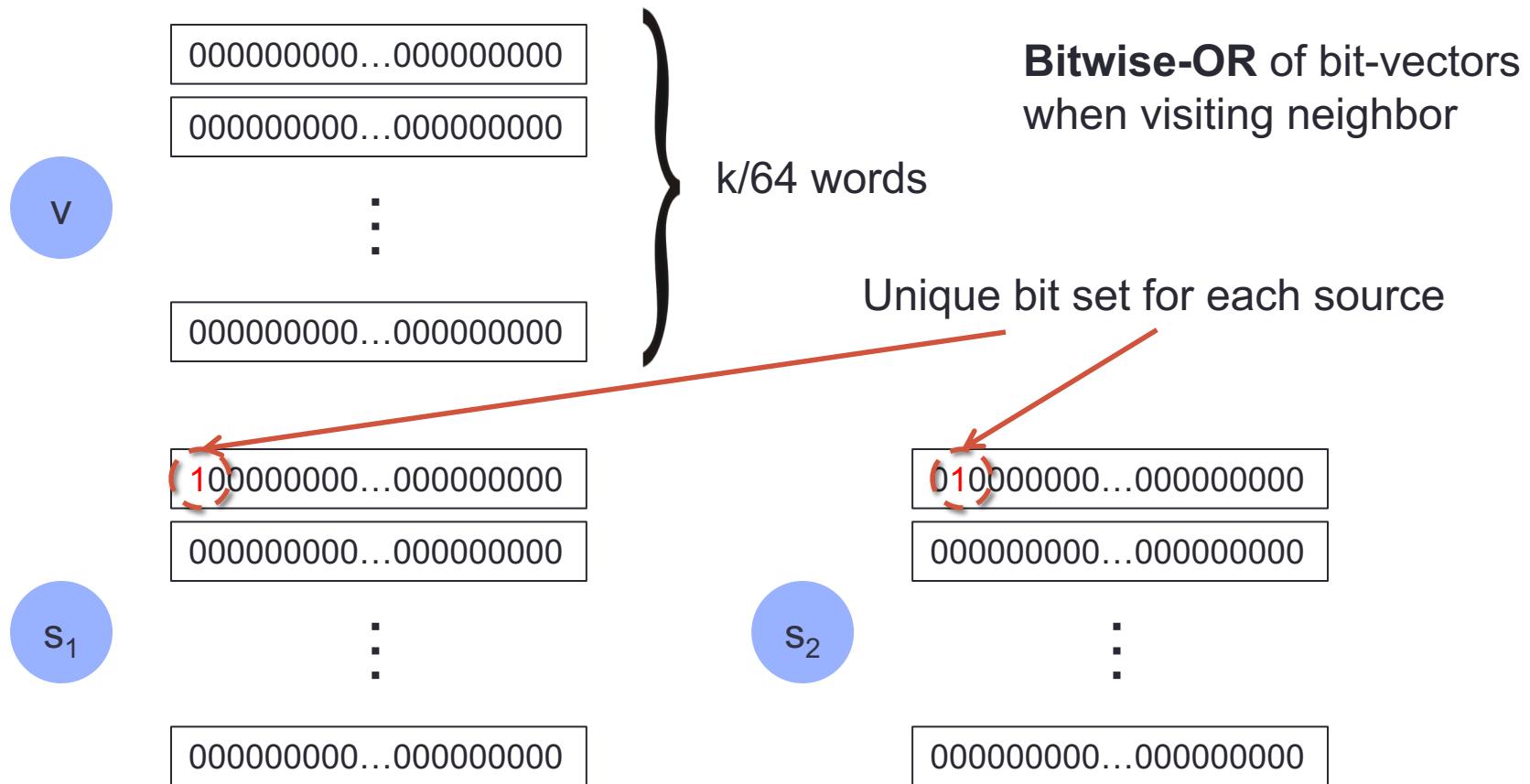
- **Observation:** There is shared work among the different BFS's



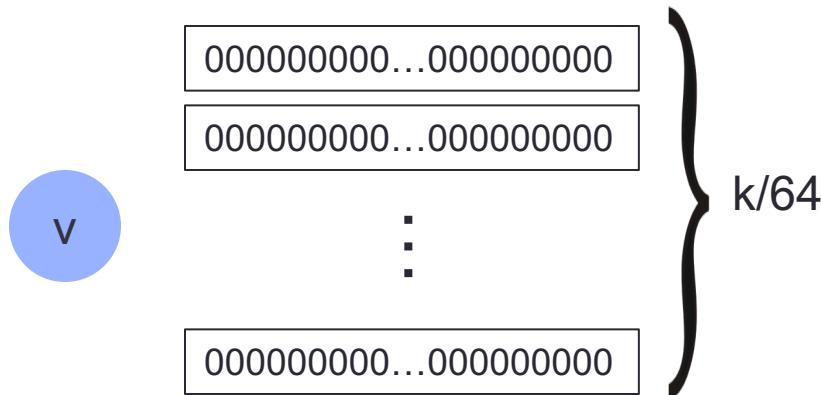
- **Goal:** Reduce redundant computation on vertices
- **Goal:** Reduce the number of times each visited vertex is placed onto the frontier

# k-BFS Implementation

- Run all k BFS's simultaneously
- Take advantage of bit-level parallelism to store “visited” information



# k-BFS Implementation

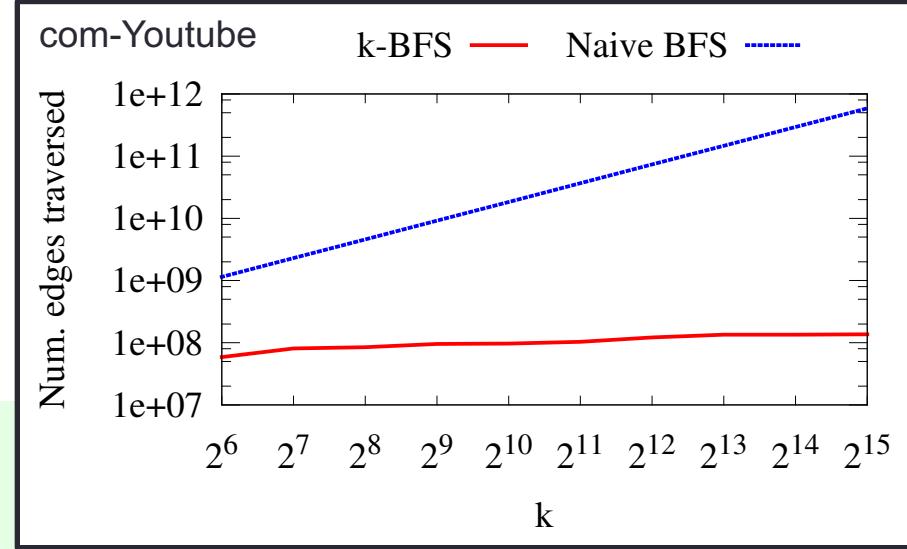


- Initial **frontier** =  $\{s_1, s_2, \dots, s_k\}$

- $d = 0$

- While **frontier** not empty:

- nextFrontier** = {}
- $d = d+1$
- For each vertex **v** in **frontier**:
  - For each neighbor **ngh**:
    - Do bitwise-OR of **v**'s words with **ngh**'s words and store in **ngh**
    - If any of **ngh**'s words changed:
      - $ecc(ngh) = \max(ecc(ngh), d)$  and place **ngh** on **nextFrontier** if not there
  - frontier** = **nextFrontier**



//Advance all BFS's by 1 level

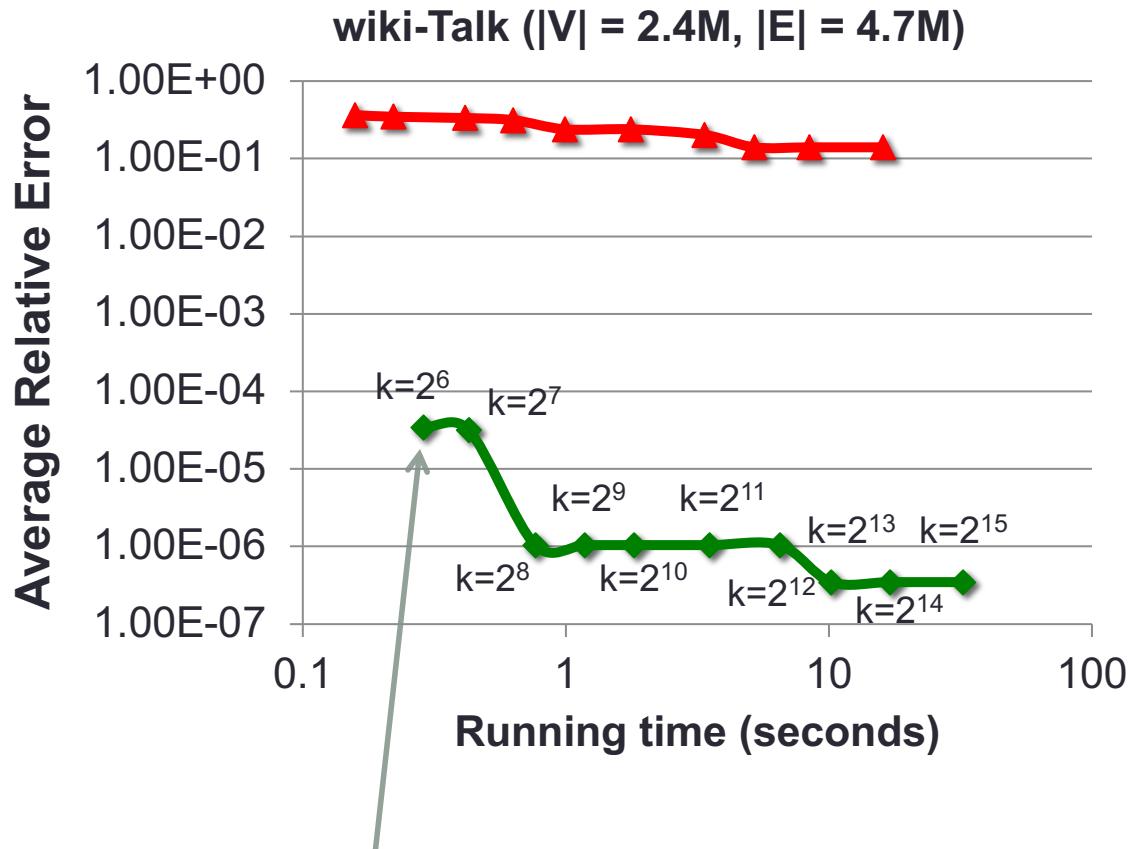
//pass “visited” information

13

# Parallel k-BFS

- Initial **frontier** =  $\{s_1, s_2, \dots, s_k\}$
  - $d = 0$
  - While **frontier** not empty:
    - nextFrontier** = {}
    - $d = d+1$
    - For each vertex  $v$  in **frontier**:
      - For each neighbor  $ngh$ :
        - Do bitwise-OR of  $v$ 's words with  $ngh$ 's words and store in  $ngh$
        - If any of  $ngh$ 's words changed:
          - $ecc(ngh) = \max(ecc(ngh), d)$  and place  $ngh$  on **nextFrontier** if not there
    - frontier** = **nextFrontier**
- //Advance all BFS's by 1 level
- 
- The diagram illustrates the parallel execution steps of the algorithm:
- atomic bitwise-OR using compare-and-swap**: This step is associated with the first part of the loop where neighbors' words are updated.
  - parallel for-loops**: This step is associated with the nested loop where each vertex in the frontier is processed, and its neighbors are updated.
  - remove duplicates**: This step is associated with the final assignment of **frontier** = **nextFrontier**, where duplicates are removed.
- //pass "visited" information
- Ligra framework that we use takes care of most details
    - User only specifies function to apply on each edge traversed
    - Performs “direction-optimizing” BFS [Beamer ‘12] automatically

# k-BFS Performance (varying k)



Experiments done on a 40-core Intel Nehalem machine with 256 GB memory

$$k = \{2^6, 2^7, 2^8, \dots, 2^{15}\}$$

k-BFS

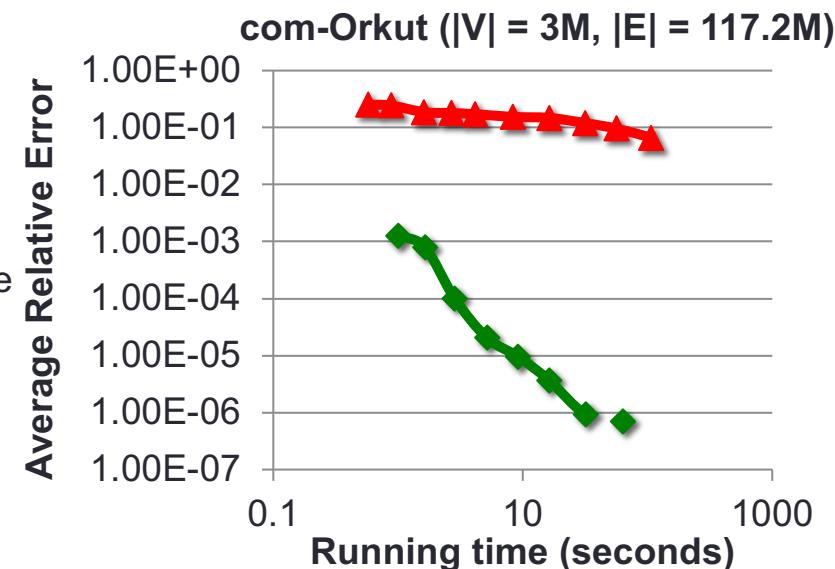
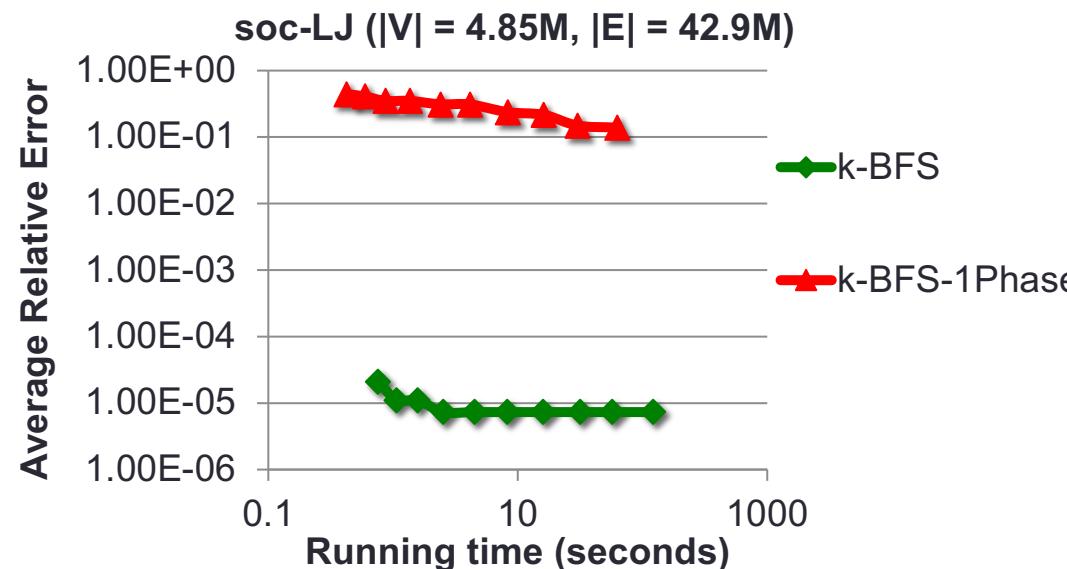
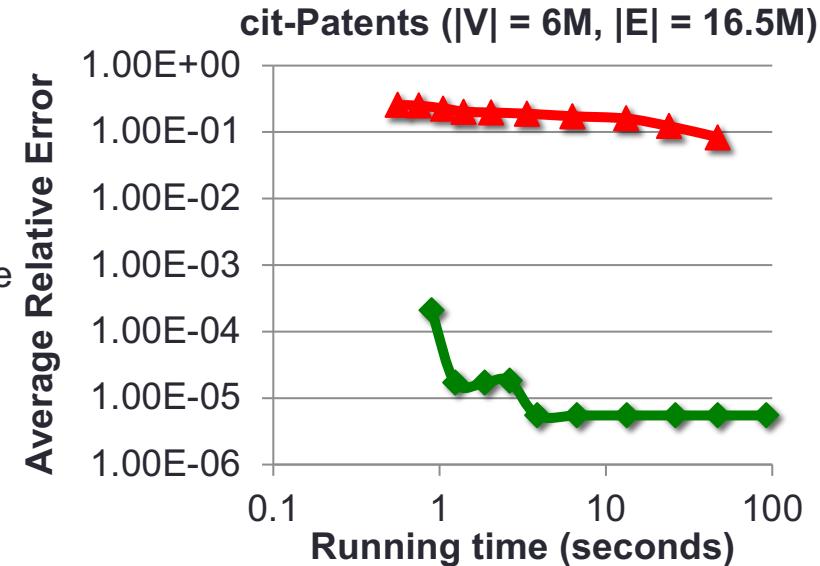
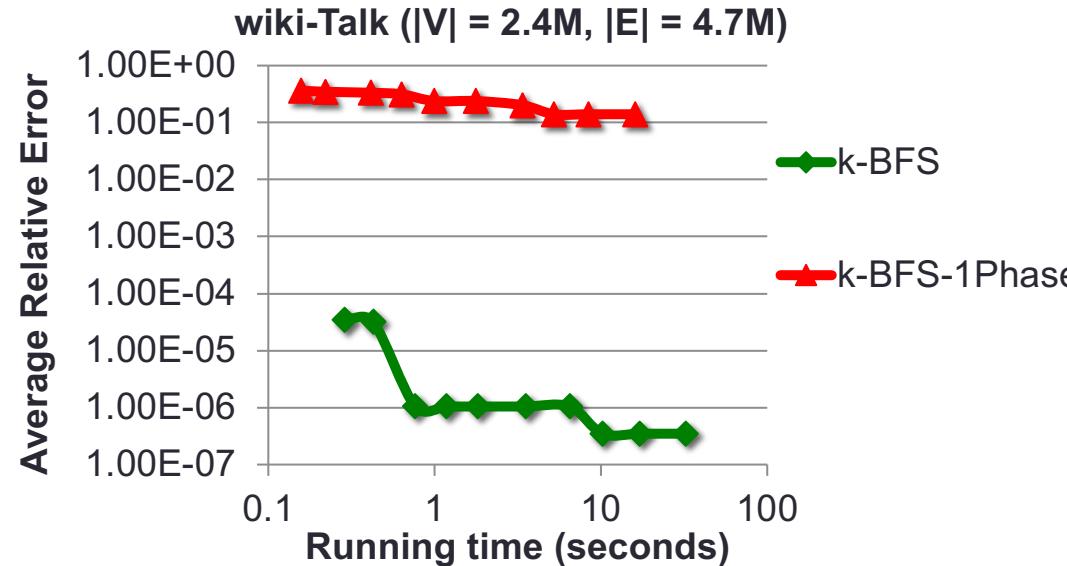
k-BFS ( $k = 64$ )

0.288 sec

$< 10^{-4}$

# k-BFS Performance

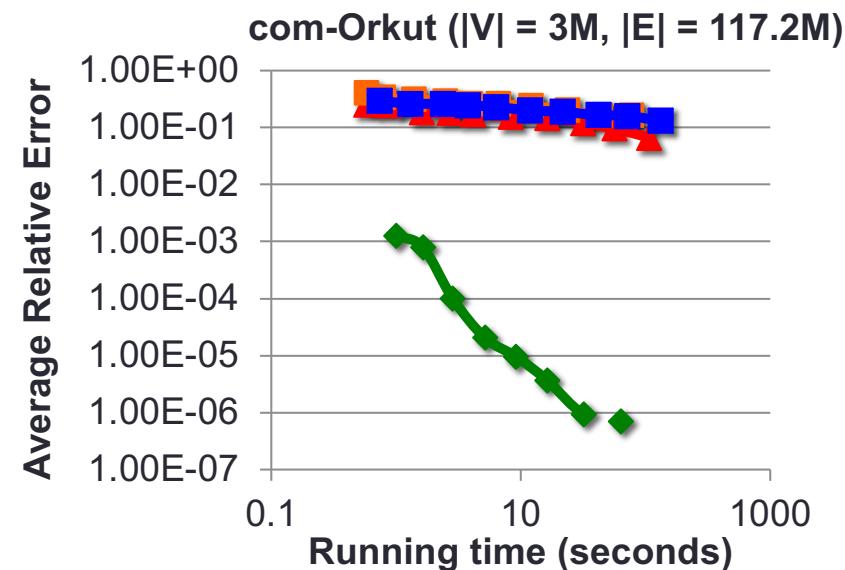
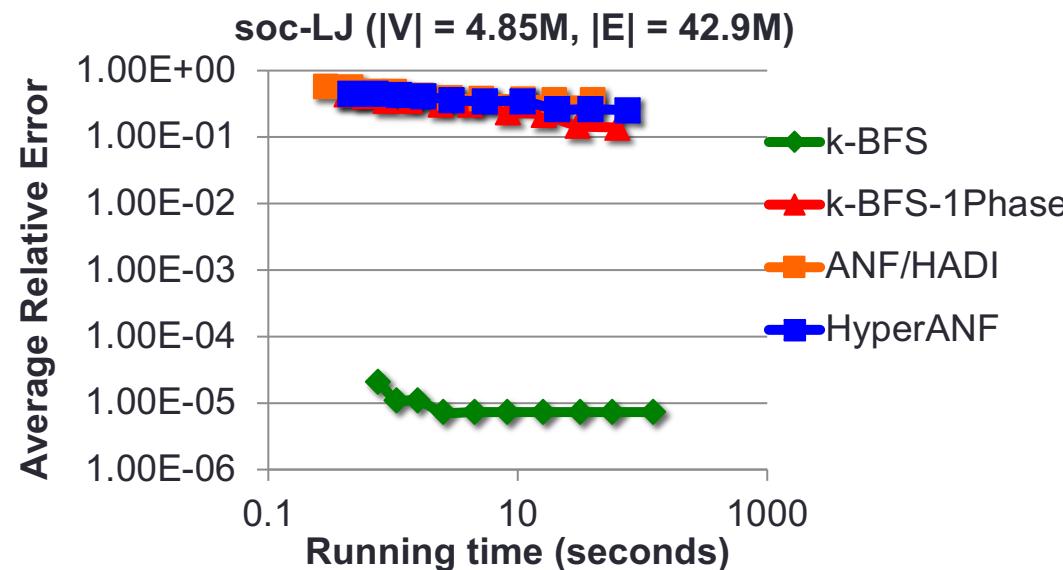
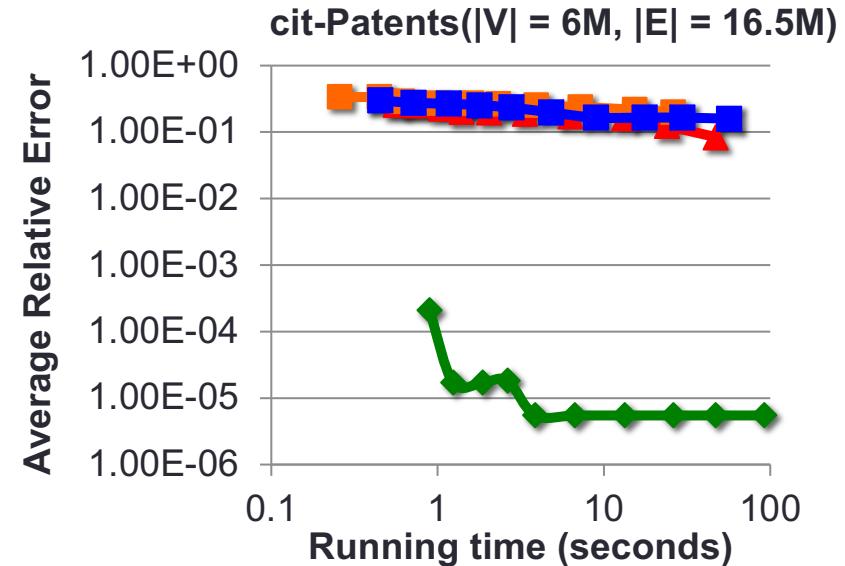
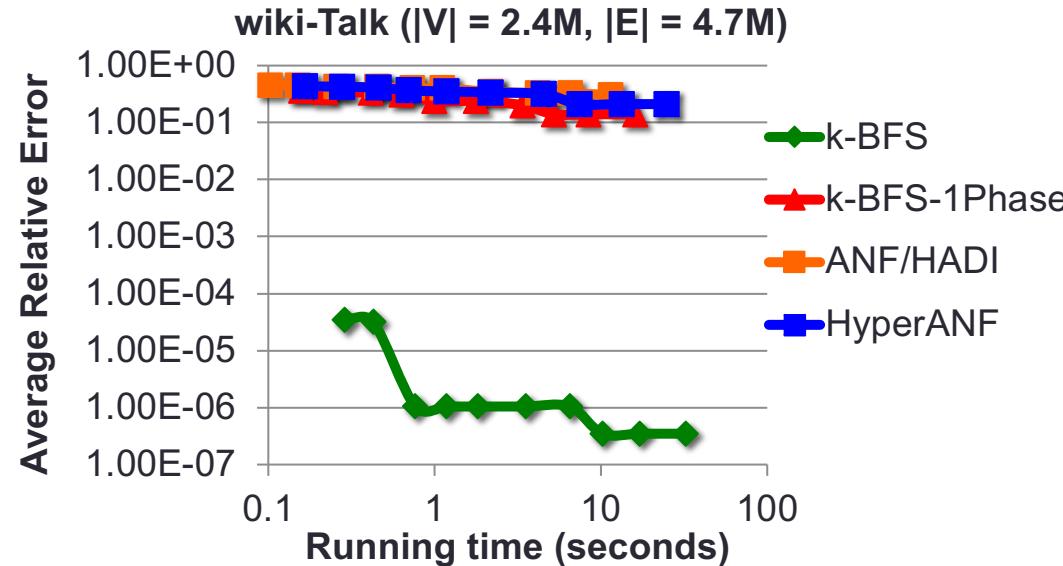
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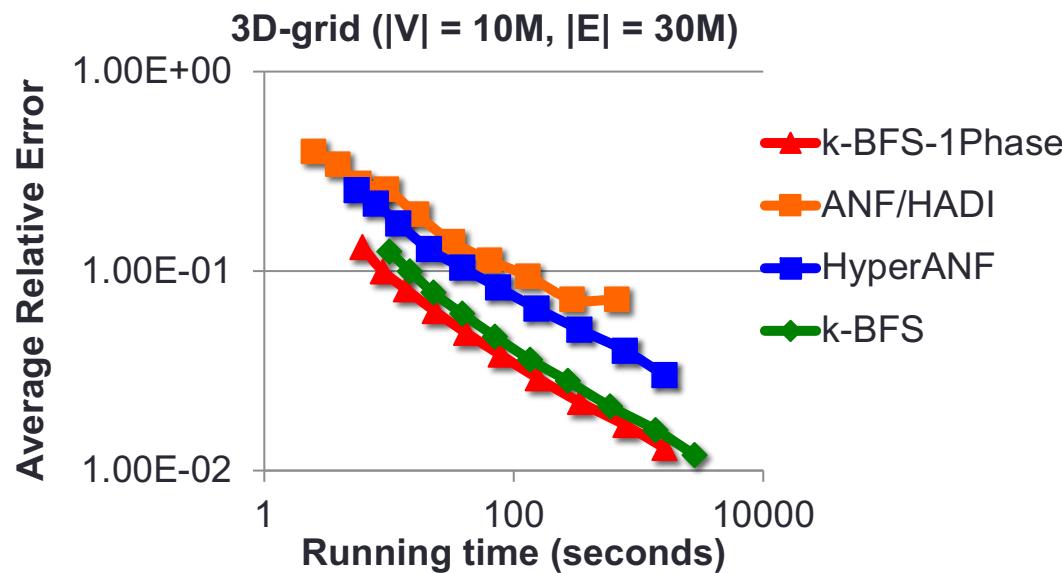
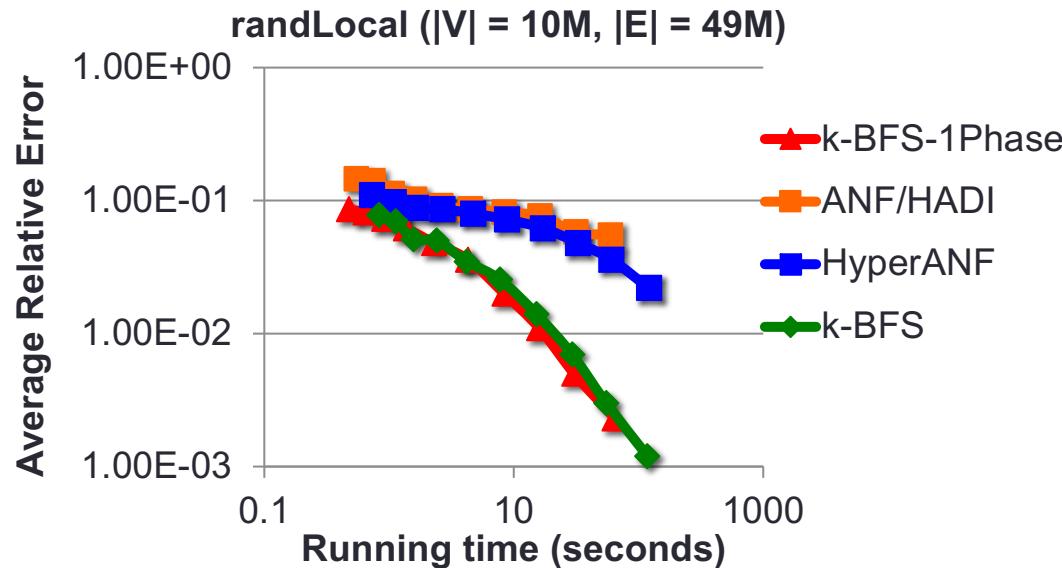
# Probabilistic Counter-based Algorithms

- Assign  $k$  probabilistic counters per vertex
- Bitwise-OR counters with all of neighbors' counters until all counters stabilize
- Eccentricity estimate for a vertex is the last round in which any of its counters changed
- ANF/HADI algorithm [Palmer et al. '03, Kang et al. '10] used Flajolet-Martin counters
- HyperANF algorithm [Boldi et al. '11] use more space-efficient HyperLogLog counters [Flajolet et al. '08]
- Shared-memory implementations of variants of ANF/HADI and HyperANF in Ligra

# k-BFS outperforms ANF/HADI and HyperANF

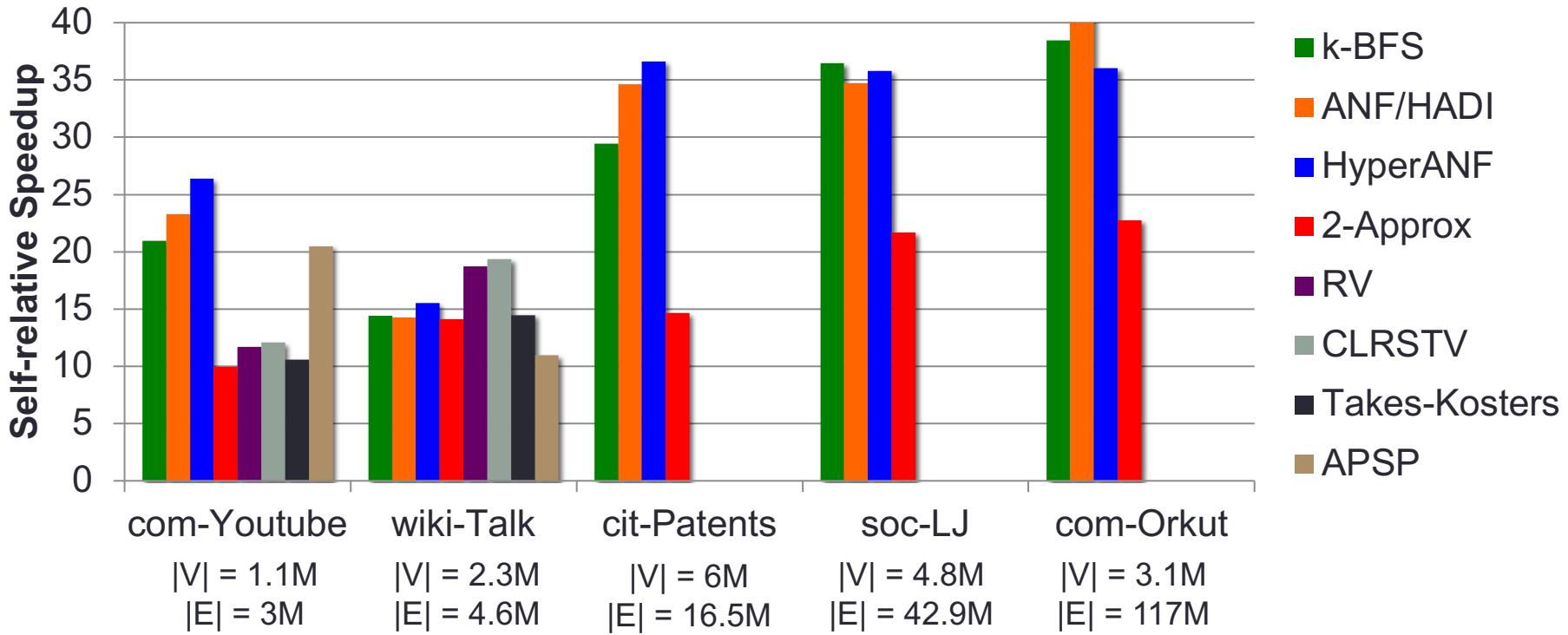


# Performance on Synthetic Graphs



# Parallel Scalability

Experiments done on a 40-core Intel Nehalem machine with 256 GB memory



- k-BFS achieves 14—38x speedup on 40 cores (higher for larger graphs)

# Scaling to Large Graphs

Experiments done on a 40-core Intel Nehalem machine with 256 GB memory



## Size

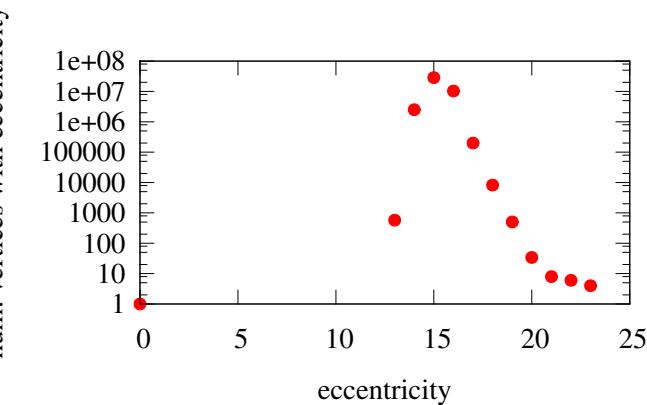
$$|V| = 4.2 \times 10^7$$

$$|E| = 1.2 \times 10^9$$

## k-BFS (k=64)

### Time

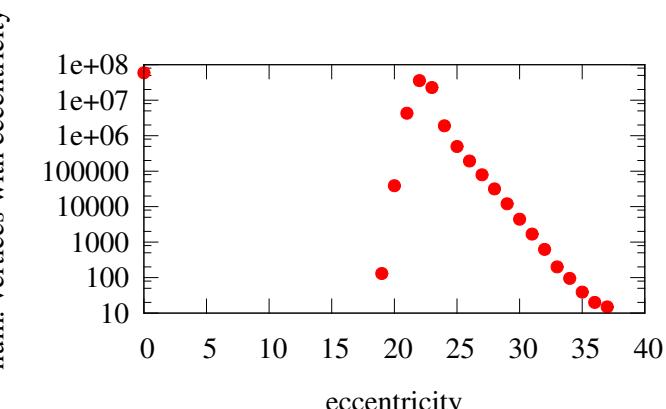
3.5 minutes



$$|V| = 1.2 \times 10^8$$

$$|E| = 1.8 \times 10^9$$

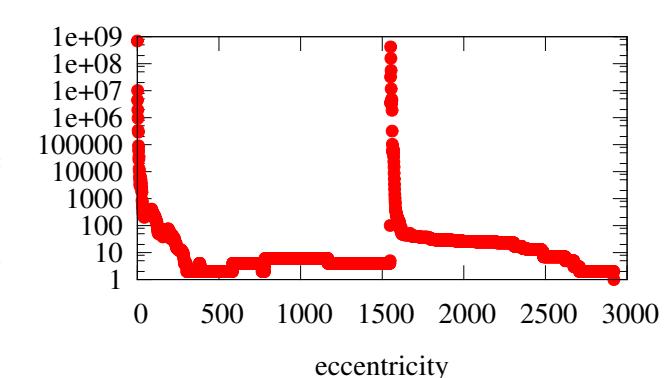
1.5 minutes



$$|V| = 1.4 \times 10^9$$

$$|E| = 6.4 \times 10^9$$

11 minutes



# Conclusion

- **Comprehensive evaluation** of shared-memory parallel eccentricity estimation algorithms
- k-BFS is orders of magnitude more **accurate** for a fixed running time than other estimation algorithms
- k-BFS is **scalable** to largest publicly-available real-world graphs studied in the literature
- Future work
  - Extensions to directed, weighted graphs
  - Theoretical bounds for (variants of) k-BFS



Thank you!

Code: <http://github.com/jshun/ligra>