Theoretically-Efficient and Practical Parallel In-Place Radix Sorting

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Why Radix Sort?

Takes O(n) work for fixed length integers.

Comparison-based sorts take $\Omega(n \log(n))$ work.

(Most Significant Digit First) Radix Sort

Radix Sort

- Sort elements according to one digit at a time.
- Most significant digit to least significant digit.
- Recurse on elements with equal digits.





Terminology: Country

Country: sub-array that will include elements belonging to the same bucket after sorting.



Radix Sort: Subproblem

Sort elements according to digits such that each element is in the correct country.



 Find start location of each country (Histogram Building).

2. Move items to the correct country inplace.

Histogram Building



Parallel Histogram Building



Initialize pointer to beginning of each country

For each country:

}

While (pointer not at end of country) {

While(item pointed to is not in correct country) {

Swap item to location pointed to in target country

Increment target country pointer



Initialize pointer to beginning of each country

For each country:

}

While (pointer not at end of country) {

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Why parallel in-place is hard?!



Why parallel in-place is hard?!



Related Work

PARADIS [Cho et. al 2015]

- Parallel in-place radix sort.
- Worst case span is O(n).

IPS4o [Axtmann et. al 2017]

- Parallel in-place comparison based sort.
- Work is O(nlog(n)).



A relaxed PIP algorithm for radix sort For some parameter K: a. Work: O(n) b. Span: O(log(K) + n/K) c. Space: O(K)

(assuming fixed length integers)

Our Algorithm: Regions Sort

Regions Sort Overview

1. Local Sorting

Partially sort the input.

2. Regions Graph Building

 Represent dependencies in partially sorted array with small amount of memory.

3. Global Sorting

 Use regions graph to completely sort the input.

Local Sorting

Key Idea:

Divide array into K *Blocks* and sort each block independently.

Block: sub-array of size n/K.



Local Sorting



Sort using serial in-place radix sort

Key Idea: Represent dependences in partially sorted array with small amount of memory.



Region: A homogeneous subarray within same current country.







Create edge of weight W from country x to country y if a region of W elements wants to go from country x to country y



Global Sorting

Key Idea: Use regions graph to move regions to their target countries iteratively and updating the graph.

Two Approaches:

Cycle Finding
 2. 2-Path Finding

Global Sorting

A 2-path consists of two edges:

- Incoming edge to node x corresponding to a region that can be moved into country x.
- Outgoing edge from node x corresponding to a region that is in country x and needs to be moved out of country x.









1. Choose a vertex.



- 1. Choose a vertex.
- 2. Match incoming edges with outgoing edges.



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- 1. Choose a vertex.
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- 3. Execute swaps.



- 1. Choose a vertex.
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- 3. Execute swaps.
- 4. Edit edges.



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2-path Finding



1. Choose a vertex.

- 2. Match incoming edges with outgoing edges.
- 3. Execute swaps.
- 4. Edit edges.





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Analysis

1. Local Sorting

a. Work: O(n)b. Span: O(log(K) + n/K)c. Space = O(KB)

- K is number of blocks
- B is number of buckets per block

Analysis

2. Build Regions Graph

- Since #edges ≤ #regions ≤ KB
- K is number of blocks
- B is number of buckets per block

3. Global Sorting

- O(n) swaps
- #nodes removed = O(B)
- #edges at each node removed is O(KB)

Total for one level of recursion

Work = O(n)Span = O(n/K + B (log(KB) + B))Space = O(KB) Recursion

Recursion

- Each country is recursed on independently.
- Each country divided into number of blocks proportional to its size.
- Integers with range r need at most log_B(r) recursion levels to be fully sorted.
- For problem sizes smaller than B, we use comparison sort.

Total on all levels

• Assuming $B = \Theta(1)$

Total on all levels

a. Work =
$$O(n)$$

b. Span = $O((\log(K) + n/K))$
c. Space = $O(P + K)$

- Assuming $B = \Theta(1)$
- Assuming $r = \Theta(1)$ (fixed length integers)

Alternative Approach: Cycle Finding

- Find Cycle in Regions Graph
- Execute Cycle to move elements
- Remove edge with min weight, and decrease weight of all other edges by this weight
- Repeat until all edges are deleted

Evaluation

Evaluation: Control Algorithms

State of the art parallel sorting algorithms:

- _gnu_parallel::sort (MCSTL, included in gcc) [Singler et. al 2007]
 Not fully in-place; uses parallel mergesort
- RADULS (parallel out-of-place radix sort) [Kokot et al. 2017]
- PBBS parallel out-of-place radix sort [Shun et. al 2012]
- PBBS parallel out-of-place sample sort [Shun et. al 2012]
- Ska Sort (serial in-place radix sort)
- IPS40 (parallel in-place sample sort) [Axtmann et al. 2017]
- PARADIS (parallel in-place radix sort) not publicly available

Input distribution:

- Uniform
- Skewed
- Equal, and almost sorted

Evaluation: Our Algorithms

Our Algorithms

Cycle finding K = P B = 256

2-path finding K = 5000 B = 256

Evaluation: Test Environment

- AWS c5.9xlarge
- Intel Xeon Platinum 8000 series
- 72 vCPU (36 cores with hyperthreading)
- 144 GB RAM
- All code compiled with g++-7 with Cilk Plus

Regions Sort performance on various inputs with 1 billion integers:

- Between 1.1-3.6x faster than IPS4o, the fastest parallel sample sort, except on one input (1.02x slower).
- Between 1.2-4.4x faster than the fastest out-of-place Radix Sort (PBBS).
- 1.3x slower to 9.4x faster than RADULS.
- About 2x faster than PARADIS based on their reported numbers on same number of cores

Speedup over serial 2-path: 1 billion random integers



Distribution independence: 1 billion integers from Zipf



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Regions Sort: fastest across all input sizes (Random)



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Input Range - Uniform Sequence (1 billion integers)



Conclusion

Our contributions:

- Regions Sort: the first parallel inplace radix sort with strong theoretical guarantees.
- Empirical evidence showing high scalability and distribution independence.
- Almost always faster than stateof-the-art parallel sorting algorithms in our experiments.